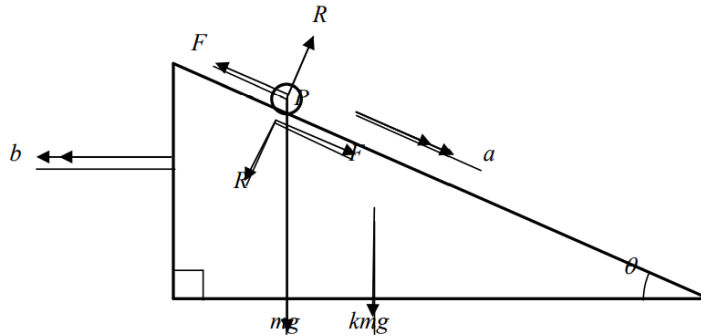


STEP II, 2008, Q11 MS

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Once again, a good, clear diagram is an important starting-point, and the above diagram shows the relevant forces – labelled using standard notations – along with the accelerations of P down the sloping surface of the wedge (a) and the wedge itself along the plane (b).

- (i) Noting the acceleration components of P are $a \cos \theta - b$ (\rightarrow) and $a \sin \theta$ (\downarrow), we employ *Newton's Second Law* as follows:

$$\begin{array}{l} \underline{N2L \rightarrow \text{for } P} \qquad m(a \cos \theta - b) = R \sin \theta - F \cos \theta \\ \underline{N2L \downarrow \text{for } P} \qquad ma \sin \theta = mg - F \sin \theta - R \cos \theta \\ \underline{N2L \leftarrow \text{for wedge}} \qquad kmb = R \sin \theta - F \cos \theta \end{array}$$

From which it follows that $a \cos \theta - b = kb \Rightarrow b = \frac{a \cos \theta}{k+1}$.

Alternatively, one could use *N2L* to note P 's \rightarrow accln. component and also the wedge's accln. \leftarrow , but instead use

CLM \leftrightarrow $km bt = m(a \cos \theta - b)t$ (where t = time from release)
and this again leads to the above result for b .

Now, for P to move at 45° to the horizontal, $a \cos \theta - b = a \sin \theta$. Then

$$b = a(\cos \theta - \sin \theta) = \frac{a \cos \theta}{k+1}$$

$$\Rightarrow (k+1)(\cos \theta - \sin \theta) = \cos \theta \Rightarrow k+1 - (k+1)\tan \theta = 1 \quad \text{and} \quad \tan \theta = \frac{k}{k+1}$$

When $k=3$, $\tan \theta = \frac{3}{4}$, $\sin \theta = \frac{3}{5}$, $\cos \theta = \frac{4}{5}$ and $b = \frac{1}{5}a$.

Substituting these into the first two equations of motion from (i), along with the use of the *Friction Law (in motion)*, which assumes that $F = \mu R$, gives

$$m\left(\frac{4}{5}a - b\right) = \frac{3}{5}R - \frac{4}{5}F \quad \text{or} \quad 3R - 4F = m(4a - 5b) = 3ma \Rightarrow R(3 - 4\mu) = 3ma$$

and

$$\frac{3}{5}ma = mg - \frac{3}{5}F - \frac{4}{5}R \quad \text{or} \quad 4R + 3F = m(5g - 3a) \Rightarrow R(4 + 3\mu) = 5mg - 3ma.$$

Dividing, or equating for R :

$$\frac{4 + 3\mu}{3 - 4\mu} = \frac{5g - 3a}{3a} \Rightarrow (12 + 9\mu)a = 5(3 - 4\mu)g - (9 - 12\mu)a \Rightarrow a = \frac{5(3 - 4\mu)g}{3(7 - \mu)}$$

- (ii) Finally, if $\tan \theta \leq \mu$, then both P and the wedge remain stationary. So, technically, the answer is “nothing”.



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